



Technical University of Łódź



Technical University of Łódź
Institute of Electronics
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IMAGE PROCESSING AND COMPUTER GRAPHICS

Python Imaging Library 3

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1 Purpose

To get acquainted with Image filtering using direct access to the pixels. The basic morphological operations will be applied to binary images. 3D image will be load into memory and selected slice will be displayed as 2D image.

Time

3×45 minutes

2 Tasks

1. Open Python interpreter window (Start → Programy → EPD32-6.0.2 → IDLE)
2. Open new Editor Window (File → New Window) and write your code into it.
3. Import needed modules, e.g. *Image*
4. Very often it is needed to get direct access to image data. Function *load()* returns a pixel access object that can be used to read and modify pixels. The access object behaves like a 2-dimensional array, so you can do:

```
pix = im.load()  
print pix[x,y]  
pix[x,y] = value
```

Create inversion of the brightness level of the *goldhill.bmp* image 1.

```
im = Image.open("goldhill.bmp")  
im = im.convert('L')  
  
sx = im.size[0]  
sy = im.size[1]  
  
pix = im.load()  
for y in range(sy):  
    for x in range(sx):  
        pix[x,y] = 255 - pix[x,y]  
  
im.save('neg.bmp')
```

5. Create an function that performs image convolution with 3×3 masks. (Hint: Designing and Implementing Linear Filters in the Spatial Domain).



(a) Gray-level image



(b) Inverted gray-level image

Figure 1: Pixel operations

```

def convolution2d (img ,k , size=3):
    """This function make image convolution with cernel .

    Kernel as a list from 0 to 8."""
    fn="convolution2d"
    print "Function %s" %fn
    pix = img.load()

    if size == 3:
        print "***Kernel size = 3"
        sx = img.size[0]
        sy = img.size[1]

        nimg = Image.new (img.mode, img.size)
        npix = nimg.load()
        val=[]
        for y in range(1,sy-1):
            for x in range(1,sx-1):
                npix[x,y]= (k[0]*pix[x-1,y-1] + k[1]*pix[x,y-1]
                            + k[2]*pix[x+1,y-1] + k[3]*pix[x-1,y]
                            + k[4]*pix[x,y] + k[5]*pix[x+1,y]
                            + k[6]*pix[x-1,y+1] + k[7]*pix[x,y+1]
                            + k[8]*pix[x+1,y+1])
    return nimg

```

Load image *blood1.bmp* and perform convolution with Prewitt masks:

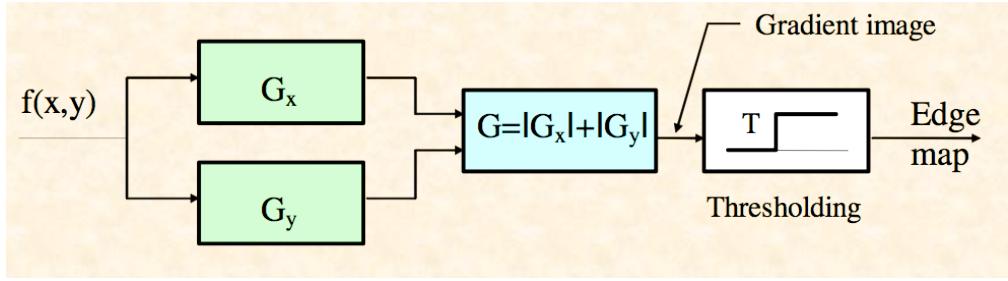


Figure 2: Edge detection procedure (from Image Processing lectures by P.Strumiłło and M.Strzelecki)

$$(a) \text{ Prewitt (horiz.)} - k1 = \begin{bmatrix} -1 & -1 & -1 \\ 0 & 0 & 0 \\ 1 & 1 & 1 \end{bmatrix} \quad (b) \text{ Prewitt (vertic.)} - k3 = \begin{bmatrix} -1 & 0 & 1 \\ -1 & 0 & 1 \\ -1 & 0 & 1 \end{bmatrix}$$

Pass convolution kernels as the function argument in the following convention:

$$k1 = [-1, -1, -1, 0, 0, 0, 1, 1, 1]$$

$$k3 = [-1, 0, 1, -1, 0, 1, -1, 0, 1]$$

Find edges of the image using procedure showed in the Fig. 2. Find appropriate threshold value (Fig. 3).

Add booth resulting images using pixel operations.

```

a1 = Image.new(im.mode, im.size)

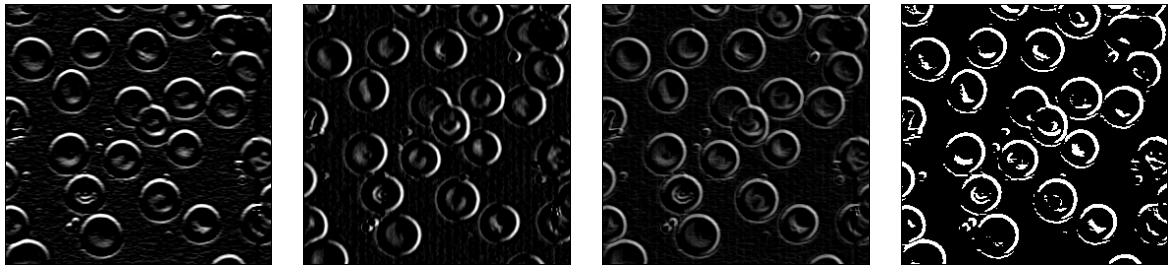
pix_a1_v = a1_v.load()
pix_a1_h = a1_h.load()
pix_a1 = a1.load()

for y in range(sy):
    for x in range(sx):
        pix_a1[x, y] = (pix_a1_h[x, y] + pix_a1_v[x, y]) / 2
    
```

6. Load images *bin1.bmp* and *bin2.bmp*. For both images apply function dilation *dilaet2D()* and erosion *erode2D()*. Use different structuring element (Fig. 4). Define each element as tuple or list, for example first element, which is *cross* shaped is defined as follows:

$$se1 = (0, 1, 0, 1, 1, 1, 0, 1, 0,)$$

Use at least 6 different structuring elements (Fig. 5).



(a) Prewitt (vert.)

(b) Prewitt (horiz.)

(c) Sum of gradients

(d) After thresholding

Figure 3: Edge detection using Prewitt mask

```

def dilate2D(im, se, sh=1):
    """dilate2D function is to do dilation of img image (2D).
    se - tuple describes any FULL_SIZE se.
    se(n) - ON piksels

    Dilation for WHITE objects with BLACK background !!! """
    fn="dilate2D(im, se)"
    if (sh): print "Function %s" %fn

    sX,sY = im.size
    imD = im.load()
    nim = Image.new(im.mode, im.size)
    nimD= nim.load()

    seX = 3 #size of se
    seY = 3
    hx = seX/2
    hy = seY/2

    for y in range(hy,sY-hy):
        for x in range(hx,sX-hx):
            if( imD[x,y] == 255 ):
                if( se[0]): nimD[x-1,y-1] =255
                if( se[1]): nimD[x, y-1] =255
                if( se[2]): nimD[x+1,y-1] =255
                if( se[3]): nimD[x-1,y] =255
                if( se[4]): nimD[x, y] =255
                if( se[5]): nimD[x+1,y] =255
                if( se[6]): nimD[x-1,y+1] =255
                if( se[7]): nimD[x, y+1] =255
                if( se[8]): nimD[x+1,y+1] =255

```

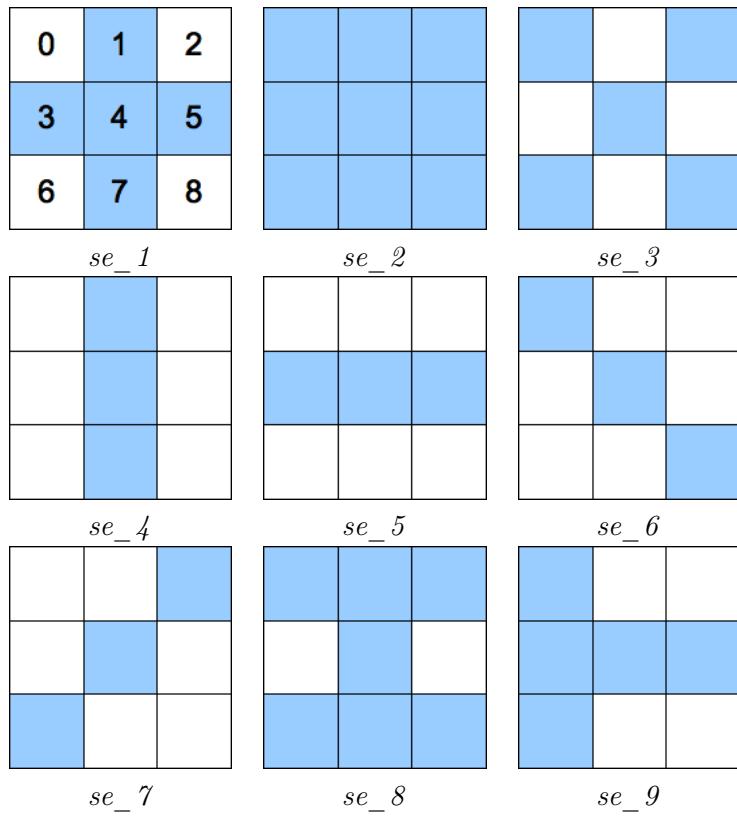


Figure 4: Various structuring elements for morphological operations

```

if(sh): print "***dilation done . . . "
return nim

def erode2D(im,se,sh=1):
    """erode2D function is to make erosion od img image (2D).
    se - tuple describes any FULL_SIZE se .
    se(n) - ON piksels

    EROSION for WHITE objects with BLACK background !!! """
fn="erode2D(im,se)"
if(sh): print "Function %s" %fn

sX,sY = im.size
imD = im.load()
nim = Image.new(im.mode, im.size)
nimD= nim.load()

```

```

seX = 3 #size of se
seY = 3
hx = seX/2
hy = seY/2

for y in range(hy,sY-hy):
    for x in range(hx,sX-hx):
        x0=[]
        if( imD[x,y] == 255 ):
            if se[0]:x0.append(imD[x-1,y-1])
            if se[1]:x0.append(imD[x, y-1])
            if se[2]:x0.append(imD[x+1,y-1])
            if se[3]:x0.append(imD[x-1,y])
            if se[4]:x0.append(imD[x, y])
            if se[5]:x0.append(imD[x+1,y])
            if se[6]:x0.append(imD[x-1,y+1])
            if se[7]:x0.append(imD[x, y+1])
            if se[8]:x0.append(imD[x+1,y+1])
            if all(x0) : nimD[x,y] = 255

        if(sh): print "***erode\_done . . . "
return nim

```

7. Define new functions for morphological opening and for morphological closing of 2D images (Fig. 6):

- *MorphologicalOpen2D(...)* which is combination of dilation and erosion of the image
- *MorphologicalClose2D(...)* which is combination of erosion and dilation of the image
- *Morphological gradient(...)* which is difference between dilation and erosion

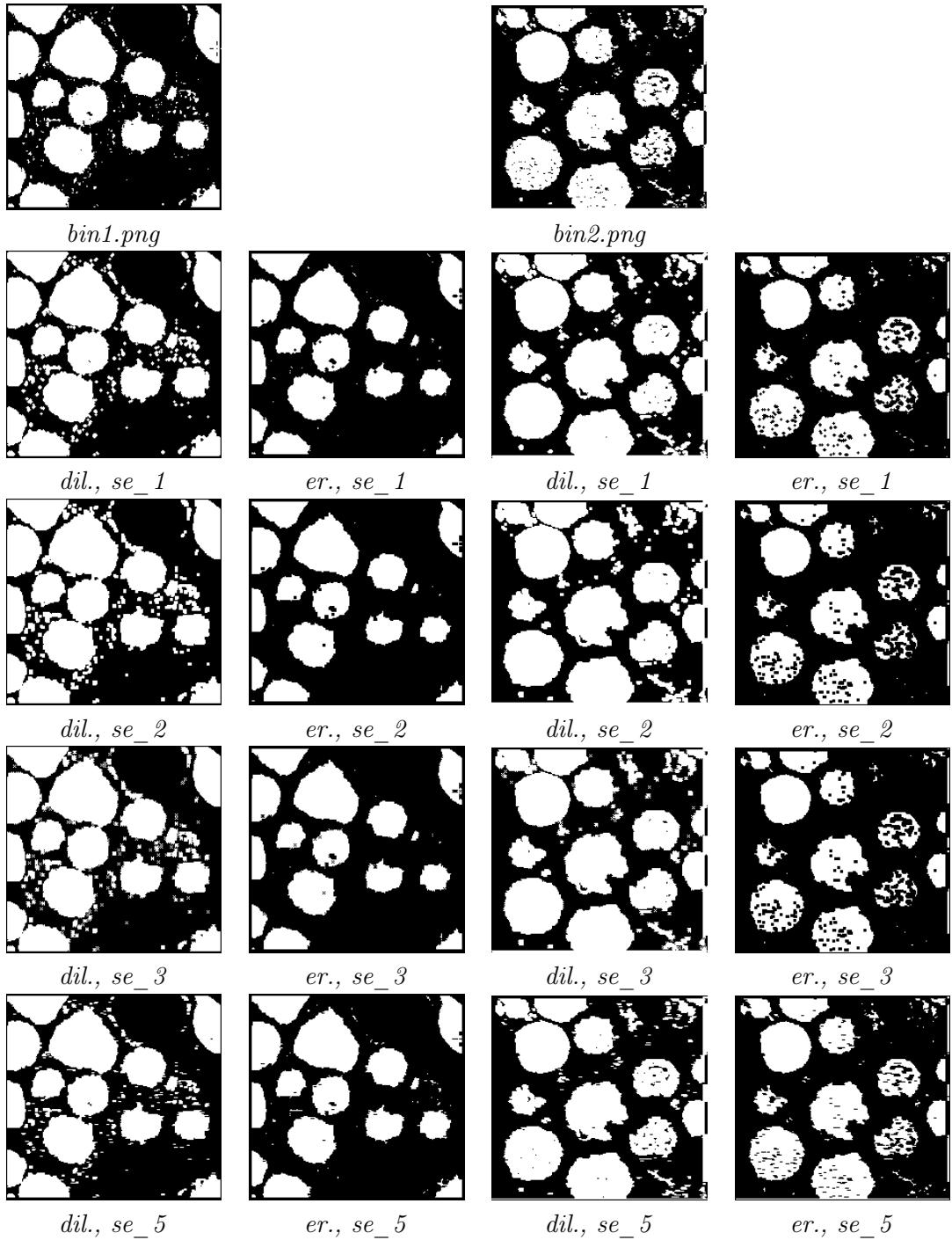
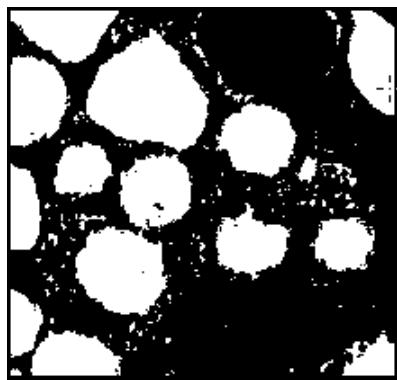
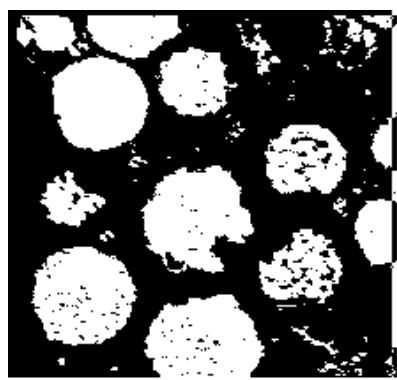


Figure 5: Results of morphological operations of image filtering with various structuring elements



(a) Oryginal image 1



(b) Oryginal image 2

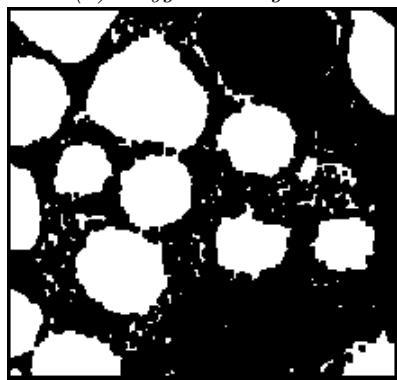


image 1 — opening

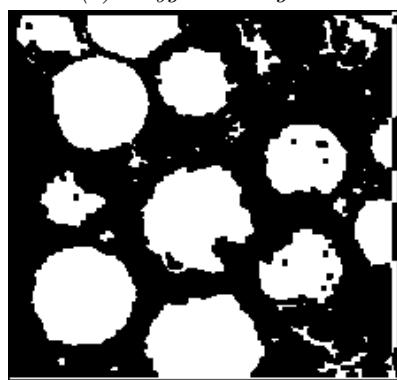


image 2 — opening

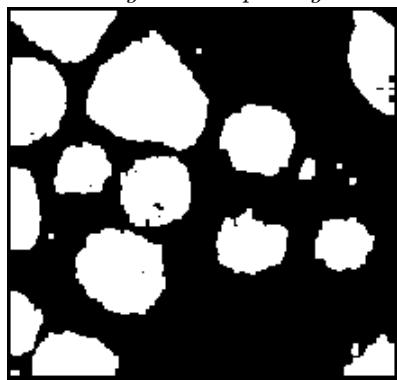


image1 — closing

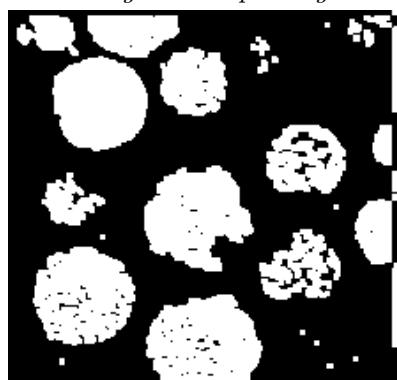


image 2 — closing

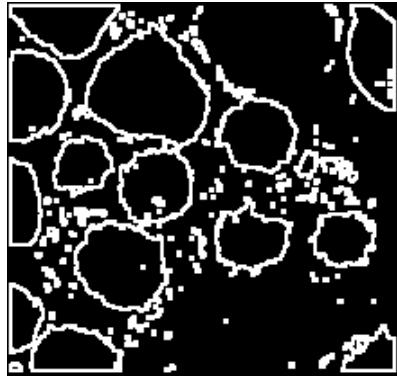


image1 — gradient

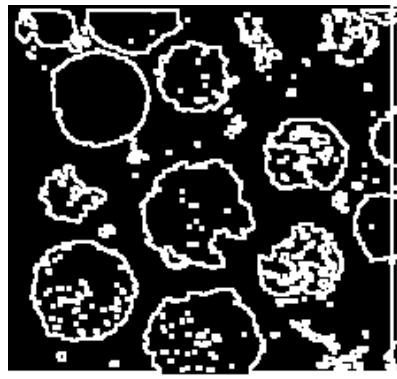


image 2 — gradient

Figure 6: Morphological operations